

Data Sheet

Programmable
Multi Transducer

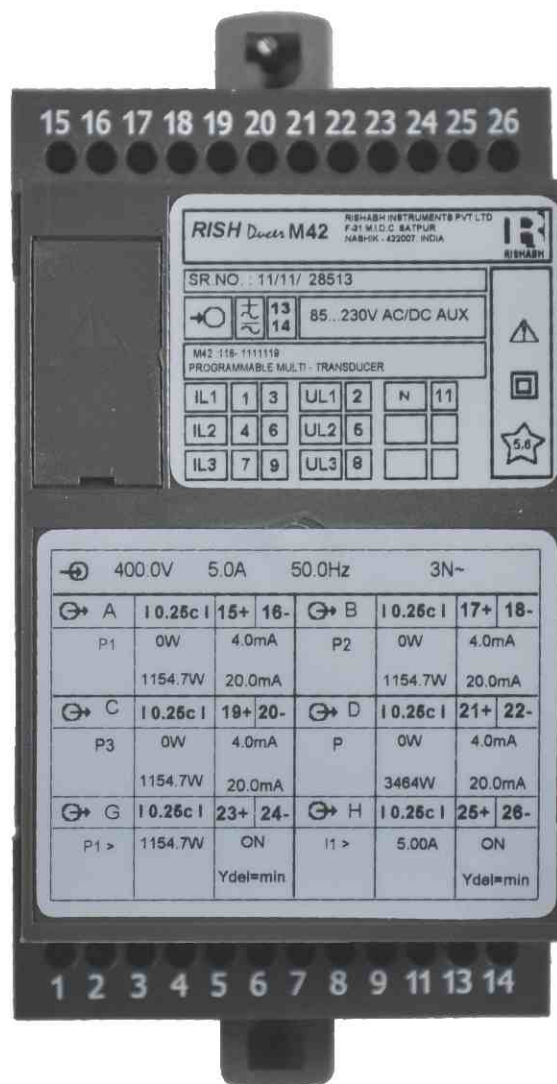


Fig. 1. The basic version universal
RISH Ducer MXX in housing clipped onto a top-hat rail.

Application

for the measurement of electrical variables in heavy current power systems

The RISH *Ducer* MXX series of multi-transducers (Fig. 1) **simultaneously** measure several variables of an electric power system and process them to produce 2 or 3 or 4 analogue output signals. 2 or 4 digital outputs are available for signaling limits or power metering. For two of the limit outputs up to 3 measurands can be logically combined.

The multi - transducers are also equipped with an serial **RS 232** interface to which a PC with the corresponding software can be connected for programming or accessing & executing useful ancillary functions. The usual modes of connection, the types of measured variables, their ratings, the transfer characteristic for each output etc. are the main parameters that have to be programmed.

Ancillary functions include a power system check, provision for displaying the measured variable on a PC monitor, the simulation of the outputs for test purposes and a facility for printing nameplates.

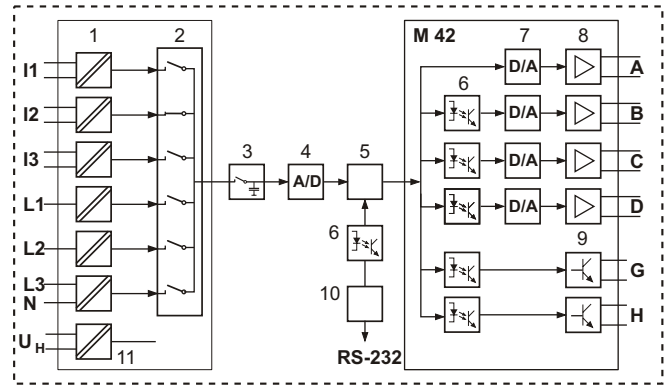
Unique Features

- For all heavy-current power system variables
- Up to 6 outputs (2A + 4D or 4A + 2D or 2A or 3A)
- Input voltage up to 693 V (phase-to-phase)
- Universal analogue outputs (programmable)
- Simultaneous measurement of several variables of a heavy-current power system / full supervision of an asymmetrically loaded four-wire power system, rated current 1 to 6 A, rated voltage 57 to 400 V (phase to neutral) or 100 to 693 V (phase-to-phase)
- High accuracy: U/I 0.2%, Frequency 0.15% and P 0.25% (under reference conditions)
- Universal digital outputs (meter transmitter, limits)
- Up to 2 or 4 integrated power meters.
- AC/DC power supply/universal (24-60V AC/DC or 85-230V AC/DC)
- Provision for either snapping the transducer onto top - hat rails or securing it with screws to a wall or panel
- Windows software with password protection for programming, data analysis, power system status simulation, acquisition of meter data and making settings

Table 1 :

Measured variables	Output	Types
Current, voltage (rms), active/reactive/ apparent power cos, sin, power factor RMS value of the current with wire setting range (bimetal measuring function)	2 analogue outputs	RISH <i>Ducer</i> M20
	3 analogue outputs	RISH <i>Ducer</i> M30
Slave pointer function for the measurement of the RMS value IB Frequency	2 analogue outputs and 4 digital outputs or	RISH <i>Ducer</i> M24
	4 analogue outputs and 2 digital outputs	RISH <i>Ducer</i> M42
Average value of the currents with sign of the active power (power system only)	4 analogue outputs and bus RS 485 (MODBUS)	RISH <i>Ducer</i> M40 *
	Data bus (LON) M00	RISH <i>Ducer</i> M00 *
	Bus RS 485 (MODBUS)	RISH <i>Ducer</i> M01 *

* Refer dedicated data sheet for complete product details.



- 1 = Input transformer
- 2 = Multiplexer
- 3 = Latching stage
- 4 = A/D converter
- 5 = Microprocessor
- 6 = Electrical insulation
- 7 = D/A converter
- 8 = Output amplifier/latching stage
- 9 = Digital output (open-collector)
- 10 = Programming interface RS-232
- 11 = Power supply

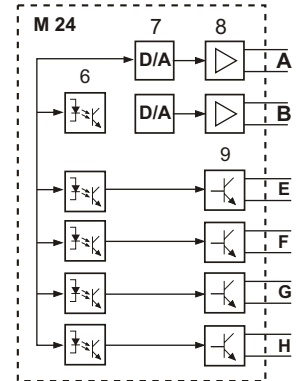


Fig. 2. Block diagram.

Table 2 : A, B, C, D = analogue outputs; E, F, G, H = digital outputs.

Models	Analog Output	Digital Output	Communication type	Programming Port
M42	4(A,B,C,D)	(E,F)	-	RS 232
M24	2(A,B)	(E,F,G,H)	-	RS 232
M20	2(A,B)	-	-	RS 232
M30	3(A,B,C)	-	-	RS 232
M00	-	-	LON Bus	RS 232
M40	4(A,B,C,D)	-	RS 485	RS 232
M01	-	-	RS 485	RS 232

Symbols and their meaning

Table 3

Symbols	Meaning
X	Measured variable
X0	Lower limit of the measured variable
X1	Break point of the measured variable
X2	Upper limit of the measured variable
Y	Output variable
Y0	Lower limit of the output variable
Y1	Break point of the output variable
Y2	Upper limit of the output variable
U	Input voltage
Ur	Rated value of the input voltage
U 12	Phase-to-phase voltage L1 - L2
U 23	Phase-to-phase voltage L2 - L3
U 31	Phase-to-phase voltage L3 - L1
U1N	Phase-to-neutral voltage L1 - N
U2N	Phase-to-neutral voltage L2 - N
U3N	Phase-to-neutral voltage L3 - N
UM	Average value of the voltages (U1N + U2N + U3N) / 3
I	Input current
I1	AC current L1

I2	AC current L2
I3	AC current L3
I _r	Rated value of the input current
I _M	Average value of the currents (I1+ I2 + I3) / 3
I _{MS}	Average value of the currents and sign of the active power (P)
I _B	RMS value of the current with wire setting range (bimetal measuring function)
I _{BT}	Response time for I _B
BS	Slave pointer function for the measurement of the RMS value I _B
B _{ST}	Response time for BS
φ	Phase-shift between current and voltage
F	Frequency of the input variable
F _n	Rated frequency
P	Active power of the system P = P1 + P2 + P3
P1	Active power phase 1 (phase-to-neutral L1 - N)
P2	Active power phase 2 (phase-to-neutral L2 - N)
P3	Active power phase 3 (phase-to-neutral L3 - N)
Q	Reactive power of the system Q = Q1 + Q2 + Q3
Q1	Reactive power phase 1 (phase-to-neutral L1-N)
Q2	Reactive power phase 2 (phase-to-neutral L2-N)
Q3	Reactive power phase 3 (phase-to-neutral L3-N)
S	Apparent power of the system $S = \sqrt{I_1^2 + I_2^2 + I_3^2} \cdot \sqrt{U_1^2 + U_2^2 + U_3^2}$
S1	Apparent power phase 1 (phase-to-neutral L1-N)
S2	Apparent power phase 2 (phase-to-neutral L2-N)
S3	Apparent power phase 3 (phase-to-neutral L3-N)
S _r	Rated value of the apparent power of the system
PF	Active power factor cos φ =P/S
PF1	Active power factor phase1 P1/S1
PF2	Active power factor phase2 P2/S2
PF3	Active power factor phase3 P3/S3
QF	Reactive power factor sin j =Q/S
QF1	Reactive power factor phase1 Q1/S1
QF2	Reactive power factor phase2 Q2/S2
QF3	Reactive power factor phase3 Q3/S3
LF	Power factor of the system LF = sgnQ (1- PF)
LF1	Power factor phase 1 sgnQ1 (1 - PF1)
LF2	Power factor phase 2 sgnQ2 (1 - PF2)
LF3	Power factor phase 3 sgnQ3 (1 - PF3)
c	Factor for the intrinsic error
R	Output load
R _n	Rated burden

Symbols	Meaning
H	Power supply
H _n	Rated value of the power supply
CT	c.t. ratio
VT	v.t. ratio

Technical data

Input

Input variables see Table 10 (Page 6) and 15 (Page 11)

Measuring ranges see Table 10 (Page 6) and 15 (Page 11)

Waveform Sinusoidal
 Rated frequency 50...60 Hz; 16 2/3 Hz
 Own consumption Voltage circuit: ≤ U² / 400 kW
 Condition: external power supply
 Current circuit: 0.3 VA I/5 A

Table 5 : Continuous thermal ratings of inputs

Current circuit	10 A 400 V single-phase AC system 693 V three-phase system
Voltage circuit	480V single-phase AC system 831V three-phase system

Table 6 :Short-time thermal rating of inputs

Input variable	Number of inputs	Duration of overload	Interval between two overloads
Current circuit	400 V single-phase AC system 693 V three-phase system		
100 A	5	3 s	5 min.
250 A	1	1 s	1 hour
Voltage circuit	1 A, 2 A, 5 A		
Single-phase AC system 600 V H _{intern} : 1.5 Ur	10	10 s	10 s.
Three-phase system 1040 V H _{intern} : 1.5 Ur	10	10 s	10 s.

Table 7 : Analogue output 

Output variable Y	Impressed DC current	Impressed DC voltage
Full scale Y2	see "Ordering information"	see "Ordering information"
Limits of output signal for input overload and/or R=0 R → ∞	see "Ordering information" 1.25 Y2 30V	see "Ordering information" 40 mA 1.25 Y2
Rated useful range of output load	$0 \leq \frac{7.5 V}{Y2} \leq \frac{15 V}{Y2}$	$\frac{Y2}{2 mA} \leq \frac{Y2}{1 mA} \leq \infty$
AC component of output signal (peak-to-peak)	≤ 0.005 Y2	≤ 0.005 Y2

The outputs A, B, C and D may be either short or open-circuited. They are electrically insulated from each other and from all other circuits (floating)

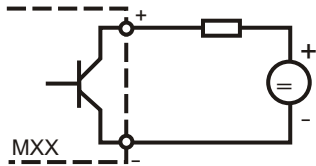
All the full - scale output values can be reduced subsequently using the programming software, but a supplementary error results. The hardware full-scale settings for the analogue outputs may also be changed subsequently. Conversion of a current to a voltage output or vice versa is also possible. This necessitates changing resistors on the output board. The full-scale values of the current and voltage outputs are set by varying the effective value of two parallel resistors (better resolution). The values of the resistors are selected to achieve the minimum absolute error. Calibration with the programming software is always necessary following conversion of the outputs. Refer to the Operating Instructions.

Caution : The warranty is void if the device is tampered.

Digital outputs, pulse outputs, limit outputs ⇨

The digital outputs conform to DIN43 864. The pulse width can be neither programmed nor is there a hardware setting.

Type of contact	Open collector
Number of pulses	see "Ordering information"
Pulse duration	≥ 100 ms
Interval	≥ 100 ms
Power supply	8 ... 40 V
Output current	ON 10 ... 27 mA OFF ≤ 2 mA



System response

Accuracy class (the reference value is the full-scale value Y2)

Table 8 :

Measured variable	Condition	Accuracy class*
System: Active, reactive and apparent power	$0.5 \leq X2/Sr \leq 1.5$ $0.3 \leq X2/Sr < 0.5$	0.25 c 0.5 c
Phase: Active, reactive and apparent power	$0.167 \leq X2/Sr \leq 0.5$ $0.1 \leq X2/Sr < 0.167$	0.25 c 0.5 c
Power factor, active power and reactive power	$0.5Sr \leq S \leq 1.5 Sr$, $(X2 - X0) = 2$	0.25 c
	$0.5Sr \leq S \leq 1.5 Sr$, $1 \leq (X2 - X0) < 2$	0.5 c
	$0.5Sr \leq S \leq 1.5 Sr$, $0.5 \leq (X2 - X0) < 1$	1.0 c
	$0.1Sr \leq S < 0.5 Sr$, $(X2 - X0) = 2$	0.5 c
	$0.1Sr \leq S < 0.5Sr$, $1 \leq (X2 - X0) < 2$	1.0 c
	$0.1Sr \leq S < 0.5Sr$, $0.5 \leq (X2 - X0) < 1$	2.0 c
AC Voltage	$0.1 Ur \leq U \leq 1.2 Ur$	0.2 c
AC current/ current averages	$0.1 Ir \leq I \leq 1.5 Ir$	0.2 c
System frequency	$0.1 Ur \leq U \leq 1.2 Ur$ resp. $0.1 Ir \leq I \leq 1.5 Ir$	$0.15 + 0.03 c$ ($f_N = 50 \dots 60$ Hz) $0.15 + 0.1 c$ ($f_N = 16 \frac{2}{3}$ Hz)
	Pulse	acc. to IEC 1036 $0.1 Ir \leq I \leq 1.5 Ir$

* Basic accuracy 0.5 c for applications with phase-shift

Duration of the measurement cycle

Approx. 0.25 to 0.5 s at 50 Hz, depending on measured variable & programming

Response time

1 ... 2 times the measurement cycle

Factor c (the highest value applies)

Linear characteristic

$$c = \frac{1 - \frac{Y0}{Y2}}{1 - \frac{X0}{X2}} \text{ or } c = 1$$

Bent characteristic

$X0 \leq X \leq X1$

$$c = \frac{Y1 - Y2}{X1 - X2} \cdot \frac{X2}{Y2} \text{ or } c = 1$$

$X1 \leq X \leq X2$

$$c = \frac{1 - \frac{Y1}{Y2}}{1 - \frac{X1}{X2}} \text{ or } c = 1$$

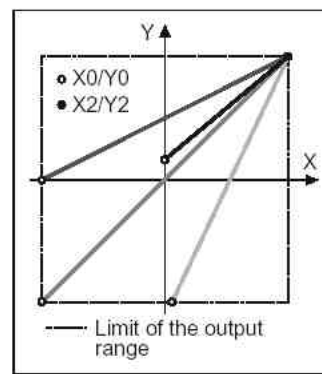


Fig. 3. Examples of settings with linear characteristic.

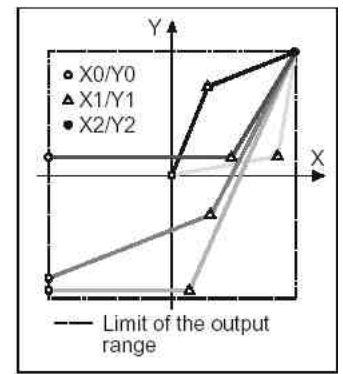


Fig. 4. Examples of settings with bent characteristic.

Reference conditions

Ambient temperature
Pre-conditioning

+ 23°C ± 1 K
30 min. acc. to DIN EN 60 688
Section 4.3, Table 2

Input variable
Power supply
Active/reactive factor
Frequency
Waveform
Output load

Rated useful range
 $H = Hn + 1\%$
 $\cos\phi = 1$ resp. $\sin = 1$
50 ... 60 Hz, 16 2/3 Hz
Sinusoidal, form factor 1.1107

DC current output:
 $R_n = \frac{7.5 V}{Y2} \pm 1\%$

DC voltage output:

$$R_n = \frac{Y2}{1 \text{ mA}} \pm 1\%$$

Miscellaneous

DIN EN 60 688

Influencing quantities and permissible variations

Acc. to DIN IEC 688

Power Supply ⇨

AC voltage

100, 110, 230, 400, 500 or 693 V, + 10%, 45 to 65 Hz
Power consumption approx. 10 VA

AC/DC power pack (DC and 50 ... 60 Hz)

Table 9: Rated voltages and tolerances

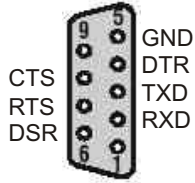
Rated voltage U_N	Tolerance
24 ... 60 V DC/AC	DC -15 ... + 33% AC ±10%
85 ... 230 V DC/AC	

Consumption:

≤ 9 W resp. ≤10VA

Programming connector on transducer

Interface RS 232 C
DSUB socket 9-pin



The interface is electrically insulated from all other circuits

Ambient conditions

Climatic rating Climate class 3 acc. to VDI/VDE3540
Variations due to ambient temperature $\pm 0.1\% / 10\text{ K}$
Nominal range of use for temperature 0...15...30...45°C (usage group II)
Storage temperature - 40 to + 850 C
Annual mean relative humidity $\leq 75\%$

Applicable standards and regulations

Table 4 :

DIN EN 60 688	Electrical measuring transducers for converting AC electrical variables into analogue and digital signals
IEC 1010 or EN 61 010	Safety regulations for electrical measuring, control and laboratory equipment
EN 60529	Protection types by case (code IP)
IEC 255-4 Part E5	High-frequency interference test (solid-state relays only)
IEC 1000-4-2,3,4,6	Electromagnetic compatibility for industrial process measurement & control equipment
VDI/VDE 3540, page2	Reliability of measuring and control equipment (classification of climates)
DIN 40 110	AC quantities
DIN 43 807	Terminal markings
IEC 68 /2-6	Basic environmental testing procedures, vibration, sinusoidal
IEC 1036	Solid state AC watt hour meters for active power (Classes 1 and 2)
DIN 43864	Current interface for the transmission of impulses between impulse encoder counter and tariff meter
UL 94	Tests for flammability of plastic materials for parts in devices and appliances

Safety

Protection class II
Enclosure protection IP 40, housing
IP 20, terminals
Overvoltage category III
Insulation test (versus earth) Input voltage : AC 400 V
Input current : AC 400 V
Output : DC 40 V
Power supply : AC 400 V
DC 230 V

Surge test
Test voltages

5 KV; 1.2/50 μs ; 0.5 Ws
50 Hz, 1 Min. according to DIN EN 61 010-1
5550 V, inputs versus all other circuits as well as outer surface
3250 V, input circuits versus each other
3700 V, power supply versus outputs and SCI as well as outer surface
490 V, outputs and SCI versus each other and versus outer surface

Vibration withstand

(tested according to DIN EN 60 068-2-6)
Acceleration $\pm 2\text{ g}$
Frequency range 10...150 10 Hz, rate of frequency sweep: 1 octave/minute
Number of cycles 10 in each of the three axes
Result No faults occurred, no loss of accuracy and no problems with the snap fastener

Installation data

Housing HousingT24
See Section "Dimensioned drawings"
Housing material Lexan 940 (polycarbonate), flammability class V-0 acc. to UL 94, self-extinguishing, non-dripping, free of halogen
Mounting For snapping onto top-hat rail (35X15 mm or 35X7.5 mm) acc. to EN 50 022 or directly onto a wall or panel using the pull-out screw hole brackets
Orientation Any
Weight With supply transformer approx. 1.1 kg
With AC/DC power pack approx. 0.7 kg

Terminals

Type Screw terminals with wire guards
Max. wire gauge $\leq 4.0\text{ mm}^2$ single wire or 2 X 2.5 mm^2 fine wire (use Taparia Screw driver-type 902)
Lugs To use flat head lugs with total metal length (J) greater than or equal to 17mm.

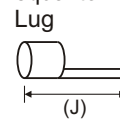


Table 10 : RISH *Ducer* MXX, standard version

The two versions of the transducer below with the **basic** programming are available AC Aux. & AC/DCAux.

Description / Basic programming		M 42	M 24	M20	M30	M40	M00	M01
Mechanical design: Rated frequency: Power supply:	Housing T24 for rail and wall mounting 50 Hz (60 Hz admissible without additional error, re-programming by user for 16 2/3Hz possible, but with additional error 1.25 c) 230 VAC 85...230 V DC/AC				<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>			
Power supply: Full-scale output signal, output A: Full-scale output signal, output B: Full-scale output signal, output C: Full-scale output signal, output D: Test certificate: Programming: Optional Display: See Table 15 : "Ordering information for MXX models" RISH <i>Ducer</i>	External connection (standard) Y2 = 20 mA Y2 = 20 mA Y2 = 20 mA Y2 = 20 mA None supplied Basic N. A.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> N. A. N. A. <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> N. A. N. A. <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> N. A. N. A. <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> N. A. N. A. <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.	<input type="checkbox"/> <input type="checkbox"/> N. A. N. A. <input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/> N. A.
Basic programming Application: Input voltage: Input current:	4-wire,3-phase system, asymmetric load(NPS) Design value Ur = 400 V Design value Ir = 5 A without specification of primary ratings				<input type="checkbox"/> <input type="checkbox"/> <input type="checkbox"/>			
Measured variable, output A: Output signal, output A:	P1; X0= 115.47 W; X2 = 115.47 W # DC current Y0 = - 20 mA; Y2 = 20 mA Linear characteristic Standard limits	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.
Measured variable, output B: Output signal, output B:	P2; X0 = - 115.47; X2 = 115.47 W # DC current Y0 = - 20 mA; Y2 = 20 mA Linear characteristic Standard limits	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.
Measured variable, output C: Output signal, output C:	P3; X0 = 115.47 W; X2 = 115.47 W # DC current Y0 = - 20 mA; Y2 = 20 mA Linear characteristic Standard limits	<input type="checkbox"/>	N. A.	N. A.	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.
Measured variable, output D: Output signal, output D:	P; X0 = - 346.41; X2 = 346.41 W# DC current Y0 = - 20 mA; Y2 = 20 mA Linear characteristic Standard limits	<input type="checkbox"/>	N. A.	N. A.	N. A.	<input type="checkbox"/>	N. A.	N. A.
Output signal, output E:	Limit P; XI = 311.77 W # Output ON if X>XI Min. pick-up delay	N. A.	<input type="checkbox"/>	N. A.	N. A.	N. A.	N. A.	N. A.
Output signal, output F:	Limit Q; XI= 34.64 var # Output ON if X>XI Min. pick-up delay	N. A.	<input type="checkbox"/>	N. A.	N. A.	N. A.	N. A.	N. A.
Measured variable, output G:	Limit P1; XI= 115.47 W # Output ON if X> XI Min. pick-up delay	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.	N. A.	N. A.	N. A.
Measured variable, output H:	Limit I1; XI = 2 A # Output ON if X> X1 Min. pick-up delay	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.	N. A.	N. A.	N. A.

Other specifications on request contact to Factory

Electrical Connections

Table 11 :

Function		Connection			
Meas. input AC current	IL1	1 / 3			
	IL2	4 / 6			
	IL3	7 / 9			
Meas. input AC Voltage	UL1	2			
	UL2	5			
	UL3	8			
	N	11			
Outputs	Analogue →○	Digital	⊖→ A	+	15
			⊖→ B	-	16
			⊖→ C	+	17
			⊖→ D	-	18
			⊖→ E	+	19
			⊖→ F	-	20
	→○	Digital	⊖→ G	+	21
			⊖→ H	-	22
			⊖→ I	+	23
			⊖→ J	-	24
			⊖→ K	+	25
			⊖→ L	-	26
Power Supply	AC	~	13		
		~	14		
	DC	+	13		
		-	14		

If power supply is taken from the measured voltage internal connections are as follow:

Table 12 :

Application (system)	Internal connection Terminal / System
Single phase AC current	2 / 11 (L1 - N)
4-wire 3-phase symmetric load	2 / 11 (L1 - N)
All other *	2 / 5 (L1 - L2)

Table 14 :

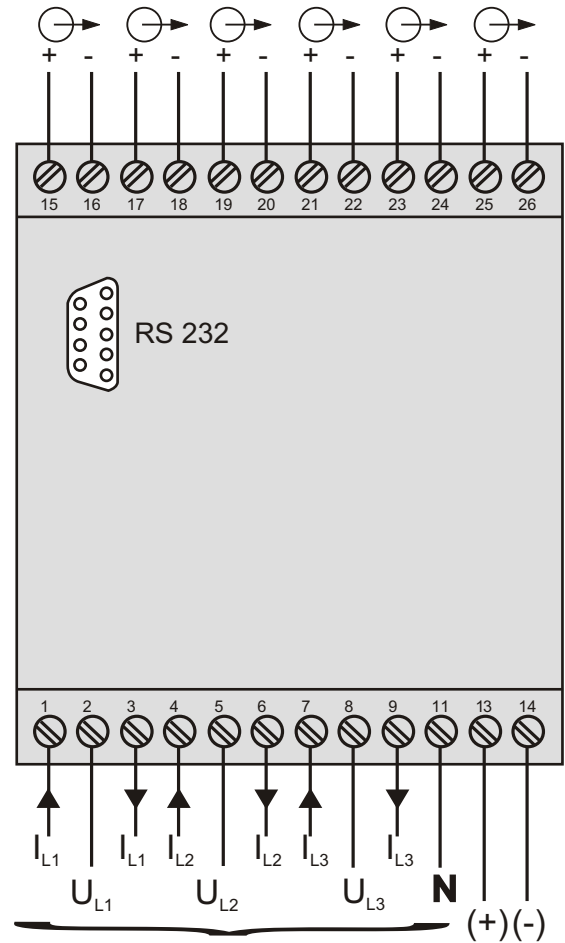
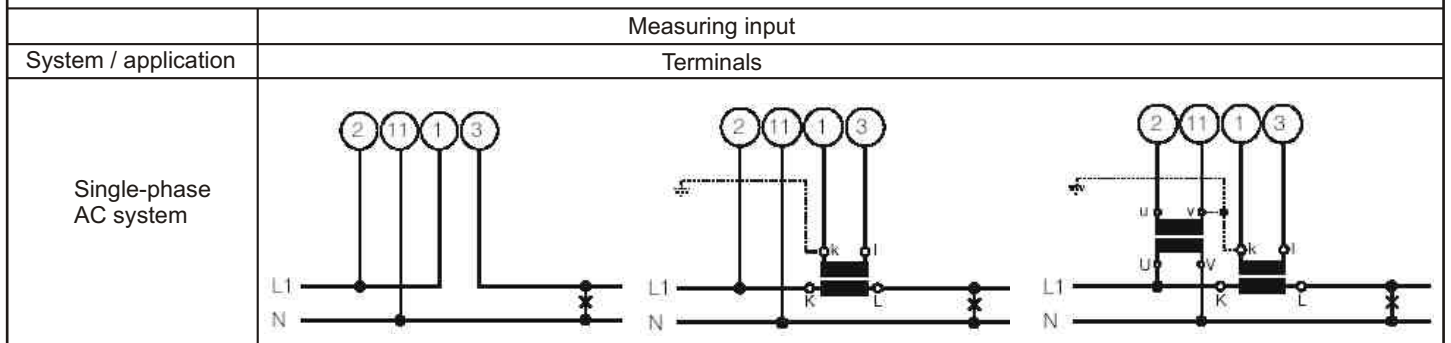


Table 13 :

	Modbus
M40	23, 24, 25, 26 (RS 485)
M00	15, 16 LON Bus
M01	23, 24, 25, 26 (RS 485)

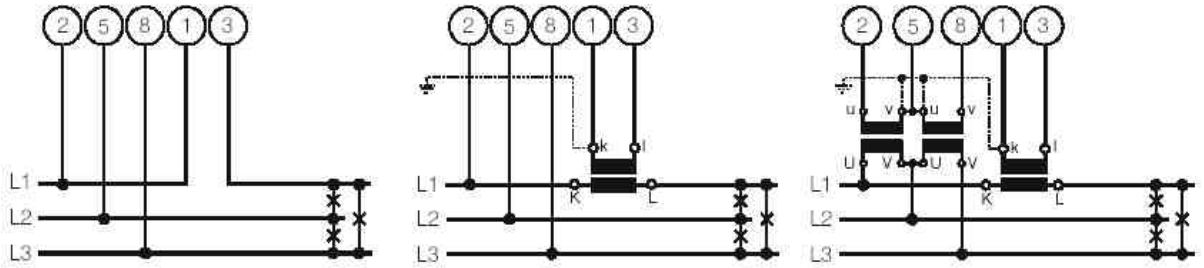
AUX Connections

Measuring input

System / application

Terminals

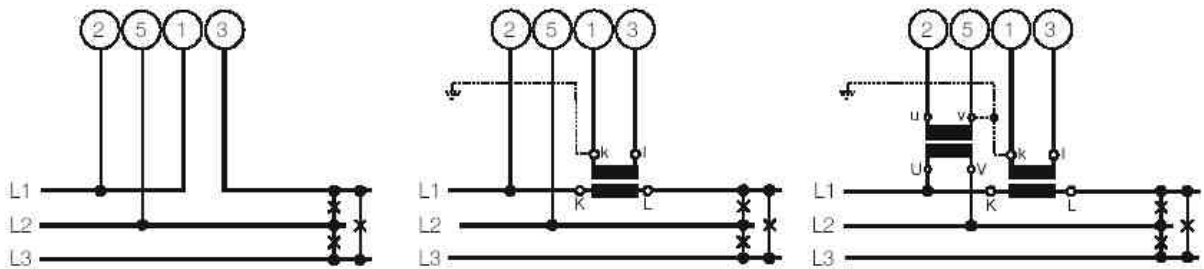
3-wire
3-phase
symmetric
load
I: L1



Connect the voltage according to the following table for current measurement in L2 or L3:

Current transformer	Terminals	2	5	8
L1	1 3	L2	L3	L1
L3	1 3	L3	L1	L2

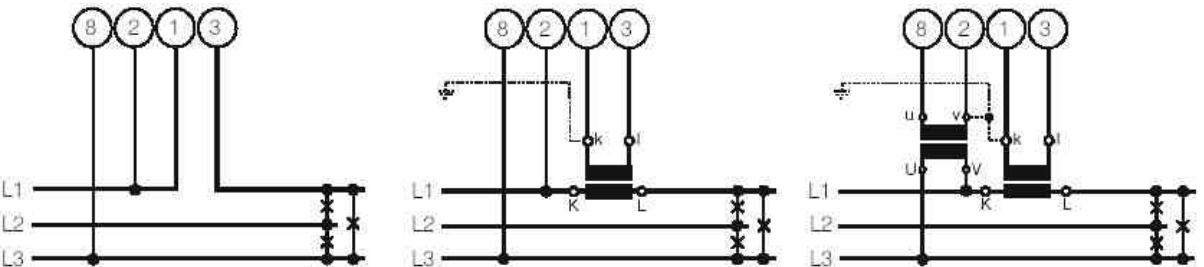
3-wire
3-phase
symmetric
load
Phase-shift
U: L1 - L2
I: L1



Connect the voltage according to the following table for current measurement in L2 or L3:

Current transformer	Terminals	2	5
L2	1 3	L2	L3
L3	1 3	L3	L1

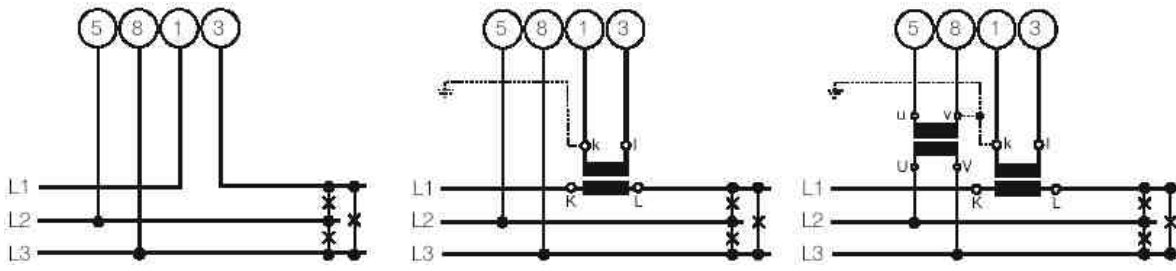
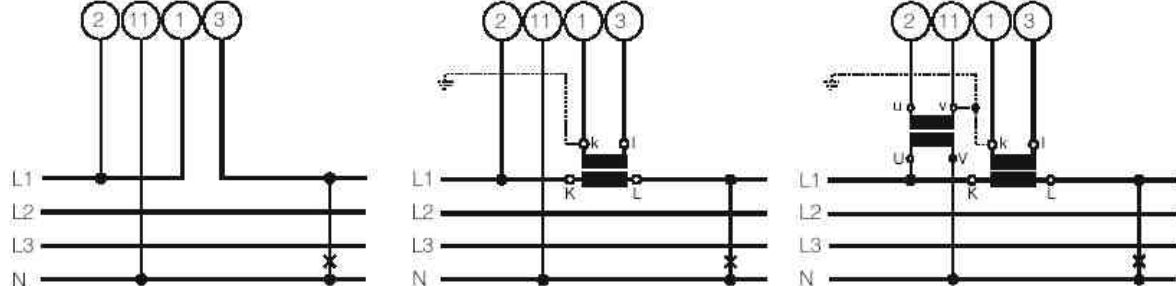
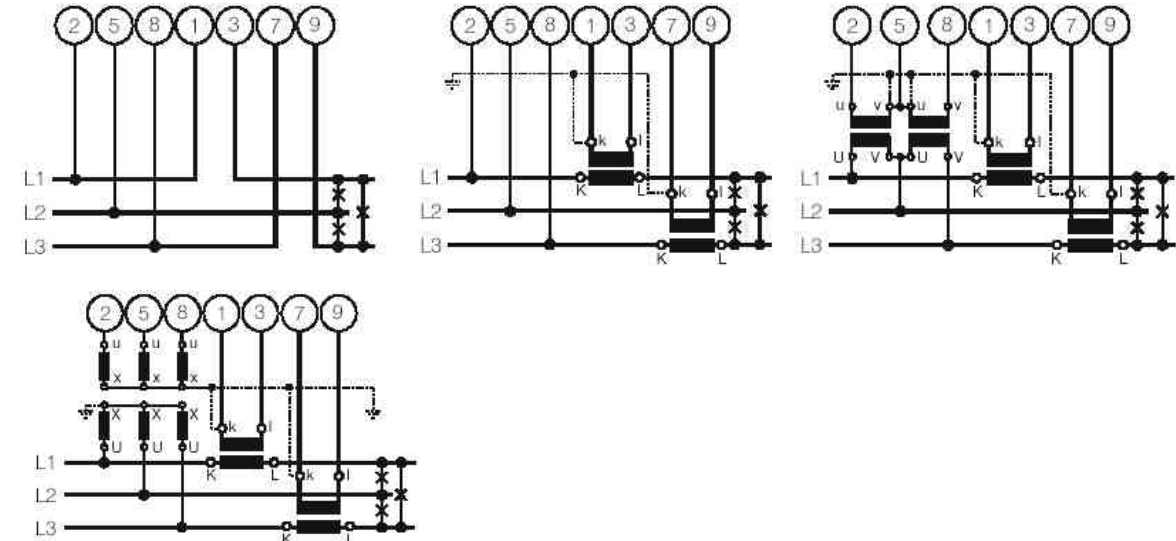
3-wire
3-phase
symmetric
load
Phase-shift
U: L3 - L1
I: L1



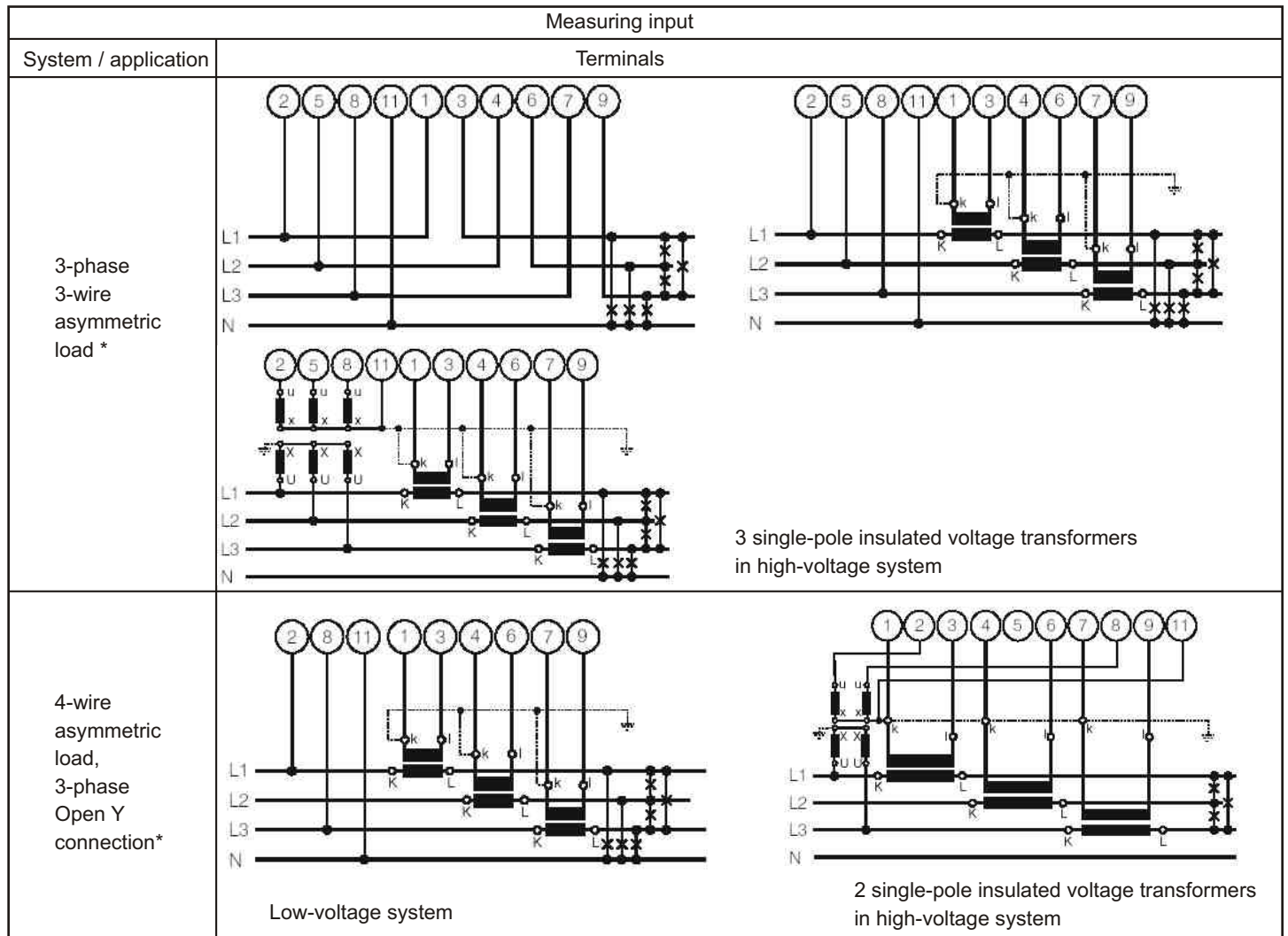
Connect the voltage according to the following table for current measurement in L2 or L3:

Current transformer	Terminals	8	2
L2	1 3	L1	L2
L3	1 3	L2	L3

Measuring input

System / application	Terminals												
3-wire 3-phase symmetric load Phase-shift U: L2 - L3 I: L1	 <p>Connect the voltage according to the following table for current measurement in L2 or L3:</p> <table border="1" data-bbox="351 515 925 616"> <thead> <tr> <th>Current transformer</th> <th>Terminals</th> <th>5</th> <th>8</th> </tr> </thead> <tbody> <tr> <td>L2</td> <td>1 3</td> <td>L3</td> <td>L1</td> </tr> <tr> <td>L3</td> <td>1 3</td> <td>L1</td> <td>L2</td> </tr> </tbody> </table>	Current transformer	Terminals	5	8	L2	1 3	L3	L1	L3	1 3	L1	L2
Current transformer	Terminals	5	8										
L2	1 3	L3	L1										
L3	1 3	L1	L2										
4-wire 3-phase symmetric load I: L1	 <p>Connect the voltage according to the following table for current measurement in L2 or L3:</p> <table border="1" data-bbox="351 985 925 1086"> <thead> <tr> <th>Current transformer</th> <th>Terminals</th> <th>2</th> <th>11</th> </tr> </thead> <tbody> <tr> <td>L2</td> <td>1 3</td> <td>L2</td> <td>N</td> </tr> <tr> <td>L3</td> <td>1 3</td> <td>L3</td> <td>N</td> </tr> </tbody> </table>	Current transformer	Terminals	2	11	L2	1 3	L2	N	L3	1 3	L3	N
Current transformer	Terminals	2	11										
L2	1 3	L2	N										
L3	1 3	L3	N										
3-phase 3-wire asymmetric load *													

* Contact to factory for complete details



* Contact to factory for complete details

Relationship between PF, QF and LF

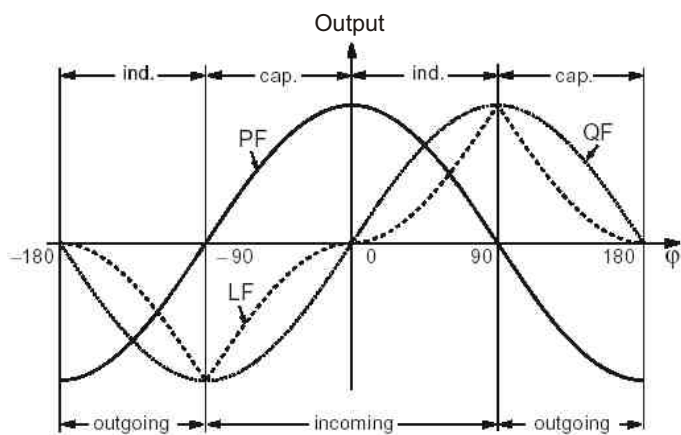


Fig. 5. Active power PF----- , reactive power QF ----- , power factor LF----- .

Dimensional Drawing

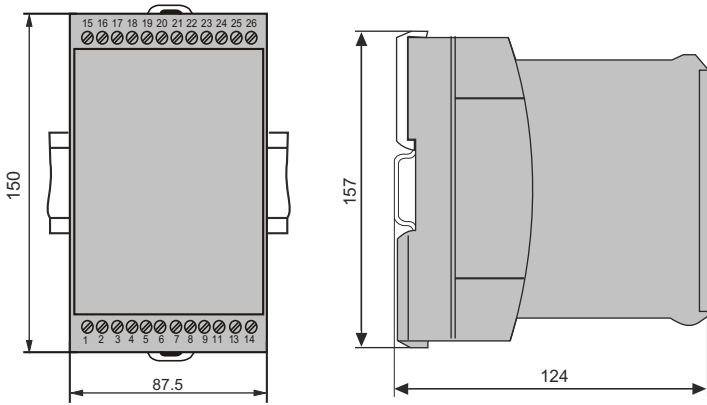


Fig. 6. RISH *Ducer* MXX in housing T24 clipped onto a top-hat rail (35 X 15 mm or 35 X 7.5 mm, acc. to EN 50 022).

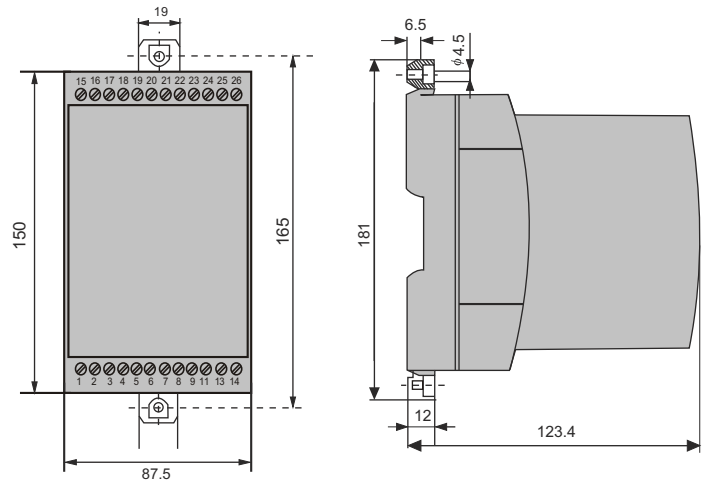


Fig. 7. RISH *Ducer* MXX in housing T24, screw hole mounting brackets pulled out.

Ordering Information

Table 15 : Ordering information for RISH *Ducer* MXX models
(see also Table 10: Standard version)

DESCRIPTION	M42	M24	M20	M30	M40	M00	M01
1. Specify the type of system (1 phase, 3 phase 3 wire / 3 phase 4 wire / balanced / unbalanced etc.) C.T. / P.T. Ratio	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>
2. Rated frequency 1) 50 Hz (60 Hz possible without additional error; 16 2/3 Hz, additional error 1.25 •c) 2) 60 Hz (50 Hz possible without additional error; 16 2/3 Hz, additional error 1.25 •c) 3) 16 2/3 Hz (not re-programming by user, 50/60 Hz possible, but with additional error 1.25 •c)				<input type="checkbox"/>	<input type="checkbox"/>		
3. Power supply 1) DC/AC 24 ... 60 V 2) DC/AC 85 ... 230 V				<input type="checkbox"/>	<input type="checkbox"/>		
4. Power supply connection 1) External (standard) 2) Internal from voltage input ** Line 2: Not available for rated frequency 16 2/3 Hz Contact Factory for further details				<input type="checkbox"/>	<input type="checkbox"/>		
5. Full-scale output signal, output A 1) Output A, Y2 =20 mA (standard) 9) Output A, Y2 [mA] <input type="text"/> * Z) Output A, Y2 [V] <input type="text"/> * Line 9: Full-scale current Y2 [mA] 1 to 20 Line Z: Full-scale voltage Y2 [V] 1 to 10	N. A.	N. A.	N. A.	N. A.	N. A.	N. A.	N. A.
	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.
	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.
	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N. A.	N. A.

* Specify separately

** Contact Factory for complete details

DESCRIPTION	M42	M24	M20	M30	M40	M00	M01
6. Full-scale output signal, output B 1) Output B, Y2 =20 mA (standard) 9) Output B, Y2 [mA] [REDACTED] * Z) Output B, Y2 [V] [REDACTED] *	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	<input type="checkbox"/>	N.A.	N.A.
7. Full-scale output signal, output C 1) Output C, Y2 = 20 mA (standard) 9) Output C, Y2 [mA] [REDACTED] * Z) Output C, Y2 [V] [REDACTED] *	<input type="checkbox"/>	N.A.	N.A.	<input type="checkbox"/>	<input type="checkbox"/>	N.A.	N.A.
8. Full-scale output signal, output D 1) Output D, Y2 =20 mA (standard) 9) Output D, Y2 [mA] [REDACTED] * Z) Output D, Y2 [V] [REDACTED] *	<input type="checkbox"/>	N.A.	N.A.	N.A.	<input type="checkbox"/>	N.A.	N.A.
9. Digital Output E Specify output i) Limit control or ii) Pulse output Also specify the parameter and their details separately	N.A.	<input type="checkbox"/>	N.A.	N.A.	N.A.	N.A.	N.A.
10. Digital Output F Specify output i) Limit control or ii) Pulse output Also specify the parameter and their details separately	N.A.	<input type="checkbox"/>	N.A.	N.A.	N.A.	N.A.	N.A.
11. Digital Output G Specify output i) Limit control or ii) Pulse output Also specify the parameter and their details separately	<input type="checkbox"/>	<input type="checkbox"/>	N.A.	N.A.	N.A.	N.A.	N.A.
12. Digital Output H Specify output i) Limit control or ii) Pulse output Also specify the parameter and their details separately	<input type="checkbox"/>	<input type="checkbox"/>	N.A.	N.A.	N.A.	N.A.	N.A.
13. Test certificate 0) None supplied 1) Supplied					<input type="checkbox"/>		
14. Programming 0) Basic 9) According to specification [REDACTED] Line 0: Not available if the power supply is taken from the voltage input					<input type="checkbox"/>		

* Specify separately

