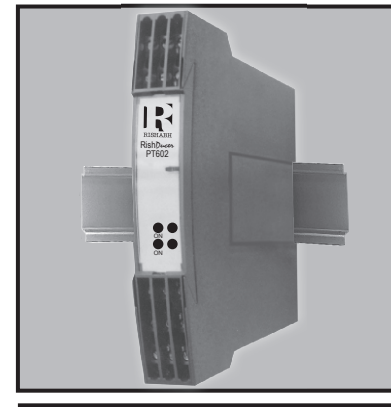


# Operating Instructions Measuring Transmitter Rish*Ducer* PT 602

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IC-1501503096657/2011

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**RISHABH**  
INSTRUMENTS  
Measure, Control & Record with a Difference

**RISHABH INSTRUMENTS LIMITED.**  
F-31, M.I.D.C., Satpur, Nashik 422 007, India.  
Tel. : +91 253 2202160, 2202202,  
Fax : +91 253 2351064  
Email : [marketing@rishabh.co.in](mailto:marketing@rishabh.co.in)  
[www.rishabh.co.in](http://www.rishabh.co.in)

# Operating Instructions

## Measuring Transmitter *RishDucer* PT 602

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### 1. Read first and then...



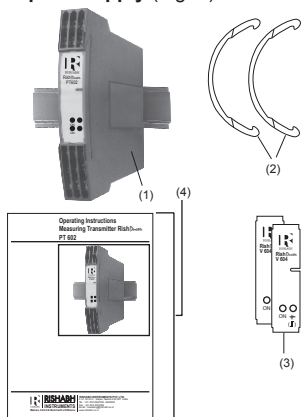
The proper and safe operation of the device assumes that the Operating Instructions are **read** and the safety warning given in the various Sections.

- 9. Mounting
- 10. Electrical connections
- 12. Commissioning

are **observed**.

The device should only be handled by appropriately trained personnel who are familiar with it and authorised to work in electrical installations.

### 2. Scope of supply (Fig. 1)



Transmitter (1)

2 Pull-out clamps (2) (for withdrawing the device from its housing)

2 Front plates (3) (for notes)

1 Operating Instructions (4) in English

### 3. Ordering informations

DESCRIPTION	MARKING
<b>1. Mechanical design</b> Housing S17	602 - 1
<b>2. Number of measuring inputs/ measuring ranges</b> With 1 meas. input / meas. range With 2 meas. input / meas. ranges	1 2
<b>3. Version / Power supply</b> Standard, 24... 60 V DC/AC Standard, 85... 230 V DC/AC	1 2
<b>4. Connection mode (applies to inputs 1 and 2)</b> Two-wire connection RL 1 [ ] RL 2 [ ] Three-wire connection Four-wire connection	1 2 3
<b>5. Measuring input 1</b> Meas. range 0...100°C, configurable Measuring range [C] - 150 to + 800 °C. span min. 50K, max. 700 K	1 9
<b>6. Measuring input 2</b> Measuring input 2 not used Meas. range 0...100°C, configurable Measuring range 2 [C] Possible measuring ranges see measuring input 1	0 1 9
<b>7. Measuring output 1 or 2 (applies to outputs 1 and 2)</b> Output 0/4...20 mA (configurable by plug-in jumpers) Output 0...10 V Output 4/0...20ma (configurable by plug-in jumpers)	1 2 3
<b>8. Certificate</b> Without test certificate With test certificate	0 1

### 4. Brief description

The measurement transmitter *RishDucer* PT 602 converts the resistance of a Pt 100 feeler to a linear output signal to the proportional to the temperature.

Depending on the version of the unit, the Pt 100 can be connected by two, three or four wires.

The desired measuring range can be set within wide limits with the aid of DIP switches and a potentiometer.

### 5. Overview of the parts

Figure 2 shows those parts of the device of consequence for mounting, electrical connections and other operations described in the Operating Instructions.

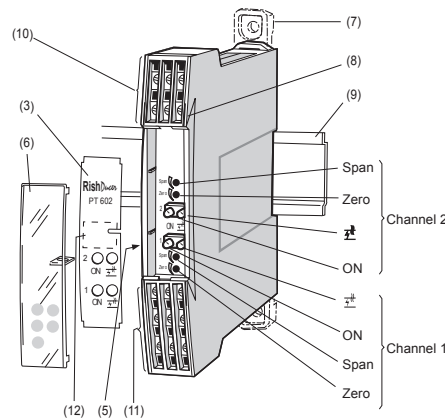


Fig. 2. The two-channel version of *RishDucer* 602

- (3) Front label
- (5) Type label
- (6) Programming connector
- (7) Fixing bracket
- (8) Opening for Pull-out clamps (for opening the housing)
- (9) Top-hat rail 35 x 15 mm or 35 x 7.5 mm (EN 50 022)
- (10) Terminals
- (11) Terminals
- (12) Space for notes
- ON Green LED's for indicating device standing by
- Red LED's for indicating operation of open-circuit or short-circuit

### 6. Technical data

#### Measuring input

Temperatures with resistance thermometer

- for two-wire connection: - 150 to + 800°C
- for three- or four-wire connection: - 170 to + 800°C

Min. span 50 K

Max. span 700 K

Measuring ranges: Set within wide limits on DIP switches and a potentiometer

Feeler current: < 1 mA

Max. lead resistance: 25 per lead (loop resistance 50 )

#### Measuring outputs

DC current : 0/4 ... 20 mA switchable

Burden voltage: 10 V

External resistance:  $R_{ext. Max.}$  500

DC voltage: 0 ... 10 V

Load capacity:  $R_{ext. min.}$  2 k

Residual ripple of output current: < 1.5% p.p.

Response time: < 500 ms

#### Open-circuit sensor circuit and short-circuit supervision

Pick-up level: - At open-circuit approx. 1 to 400 k

- At open-circuit approx. 0 ... 30

Fault signalling mode: - Frontplate signals  
Red LED for signalling fault

- Output signal at 0/4...20 mA, output approx. 25 mA at 0...10V, output approx. 12.5 V

#### Power supply

AC/DC power pack (DC and 45 ...400 Hz)

Table 1: Rated voltages and permissible variations

Nominal voltages $U_N$	Permissible variation
24... 60 V DC / AC	DC - 15... + 33%
85...230 V <sup>1</sup> DC / AC	AC 15 %

<sup>1</sup> An external supply fuse must be provided for DC supply voltage >125 V.

Power consumption: 1.8 W resp. 3.4 VA

#### Accuracy data (acc. to DIN/IEC 770)

Basic accuracy: Max. error 0.5% including linearity and repeatability errors

#### Installation data

Terminals: DIN/VDE 0609  
Screw terminals with wire guards for light PVC wiring and max. 2 x 0.75 mm<sup>2</sup> or 1 x 2.5 mm<sup>2</sup>  
Screw M2.5 torque is 0.4 N-m

Permissible vibrations: 2 g acc. to EN 60 068-2-6

Shock: 50  
3 shocks each in 6 directions acc. to EN 60 068-2-27

**Electrical insulation:** All circuits (measuring inputs/ measuring outputs / power supply) are electrically insulated.

**Standards**

Housing protection (acc. to IEC 529 resp. EN 60 529): IP 40  
Terminals IP 20

Electrical standards: Acc. to IEC 1010 resp. EN 61 010

Test voltage: Power supply versus:  
- all 3.7 kV, 50 Hz, 1 min.  
Measuring inputs versus:  
- Measuring outputs 2.3 kV, 50 Hz, 1 min.  
Measuring inputs versus:  
- Measuring outputs 2.3 kV, 50 Hz, 1 min.  
Measuring inputs 1 versus:  
- Measuring outputs 2 2.3 kV, 50 Hz, 1 min.

**Environmental conditions**

Commissioning temperature: - 10 to + 55°C  
Operating temperature: - 25 to + 55°C  
Storage temperature: - 40 to + 70°C  
Annual mean relative humidity: 75%

After replacing the label in the transparent cover, the transparent cover can be snapped into the front of the device again. This is done by inserting it behind the edge at the bottom and pressing it gently down and to the rear with the finger until it snaps into place (right side of Fig. 3)

**8. Withdrawing and inserting the device**

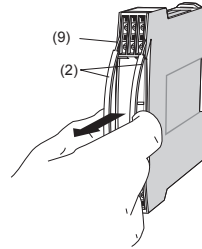


Fig. 5

Insert the pull-out clamps S17 (2) into the openings (9) until they snap into place. Withdraw the front part together with the main PCB out of the housing.

To reassemble the unit, insert the front part together with the main PCB into the housing until the swallow-tailed sections engage in each other.

**9. Mounting**

The RishDucer PT 602 can be mounted either on a top-hat rail or directly onto a wall or mounting plate.

Make sure that the ambient temperature stays within the **permissible limits:**  
-25 and + 55°C

**7. Exchanging frontplates**

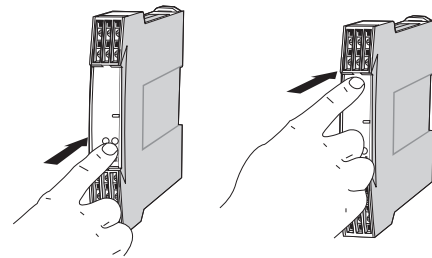


Fig. 4 Left : Removing the transparent cover  
Right : Inserting the transparent cover

Apply gentle pressure to the transparent cover as shown in Fig. 4 until pops out on the opposite side. The label in the cover can be replaced and used for notes.

**9.1 Top-hat rail mounting**

Simply clip the device onto the top-hat rail (EN 50 022) (see Fig. 6).

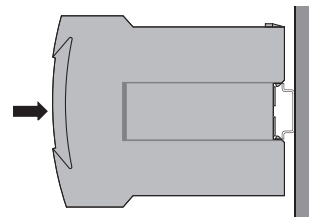


Fig. 6. Mounting on top-hat rails 35 x 15 or 35 x 7.5 mm.

**9.2 Wall mounting**

Drill 2 holes in the wall or panel as shown in the drilling pattern (Fig.6). Now secure the power pack to the wall or panel using two 4 mm diameter screw.

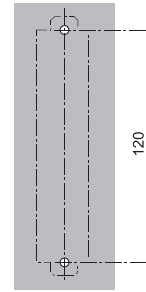


Fig. 6. Drilling pattern.

The while pressing the latch (18) in the base of the device (Fig. 8, left), pull out the transmitter securing brackets (10). Now secure the transmitter to the wall or panel using two 4 mm diameter screws.

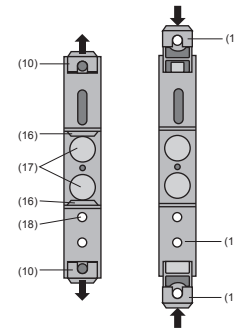


Fig. 7. Rear of device.  
(10) Screw hole brackets  
(16) Top-hat rail clip  
(17) Rubber buffers  
(18) Latch for pulling the screw hole brackets out  
(19) Latch for pushing the screw hole brackets in

**Note :**  
To return the brackets to their original positions, the latch (19) in the base of the device has to be depressed before applying pressure to the securing brackets (10) (see Fig. 7, right).

**10. Electrical connections**

The electrical connections are made to screw terminals which are easily accessible from the front of the transmitter and can accommodate wire gauges up to 1 x 2.5 mm.

Make sure that the cables are not live when making the connections !  
**The 230V power supply and 250 V contact output is potentially dangerous.**

Note that , ...  
... the data required to carry out the prescribed measurement must correspond to those marked on the nameplate of RishDucer PT 602 (⊖ input E, ⊕ output A and → power supply H) !  
... the total loop resistance connected to the output (receiver plus leads) **does not** exceed the maximum permissible value  $R_{max}$ . See "Measuring output" in Section "5. Technical data" for the maximum values of  $R_{max}$  !  
... the signal input and output cables should be twisted pairs and run as far as possible away from heavy current cables !

In all other respects, observe all local regulations when selecting the type of electrical cable and installing them!

Front

<p style="text-align: center;">Without transparent cover</p>	<p style="text-align: center;">With transparent cover</p>
--	---

● ON  
Green LED's for indicating device standing by

●  $\overline{ON}$   
Red LED's for indicating operation of open-circuit or short-circuit

Terminal allocation acc. to connection mode. see Table 2

3	4	8	9	1	2	6	7	13	14	11	12	5	10
⊖				⊖				-		+		~	
E1				E2				A1		A2		H	

Table 2: Connections of the measuring input leads E1 and E2

Measuring inputs		Connecting mode*	Connecting diagram Terminal arrangement
Version with 1 input and 1 output	Measuring input $\rightarrow$ E1	Two-wire connection	
		Three-wire connection	
		Four-wire connection	
Version with 2 inputs and 2 outputs	Measuring input $\rightarrow$ E1	Two-wire connection	
		Three-wire connection	
		Four-wire connection	
Version with 2 inputs and 2 outputs	Measuring input $\rightarrow$ E2	Two-wire connection	
		Three-wire connection	
		Four-wire connection	

RishDucer PT 602 units with the designations 602-1XX1 and 602-1XX2 can operate with either two-or three-wire connections, but units with the type designation 602-1XX3 only operate with a four-wire connection.

## Notes

### 10.1 Connection to resistance thermometers

#### 10.1.1. Two-wire connection (connection diagram Table 2)

Connect terminals 3 and 8 on the single-channel version for a two-wire connection to the feeler.

Connect terminals 3 and 8 and also 1 and 6 on the two-channel version. A resistance up to 25  $\Omega$  per lead is permissible which is taken into account during configuration (see Section 11.2.2.)

#### 10.1.2. Three-wire connection (connection diagram Table 2)

It is assumed that the three leads of a three-wire connection have identical resistance and no compensation is necessary. The lead resistance must not be greater than 25  $\Omega$  per lead.

#### 10.1.3. Four-wire connection (connection diagram Table 2)

The four-wire measurement is independent of lead resistance within wide limits and therefore no compensation is necessary. The lead resistance must not be greater than 25  $\Omega$  per lead.

### 10.2 Measuring output leads

Connect the output leads for output A1 to terminals 13(-) and 14(+) and for output A2 (field indicator) to terminals 11 (-) and 12(+) acc. to Section "10. Electrical connections".

Note! The maximum permissible external resistance  $R_{ext}$  max. of the RishDucer PT 602 must not be exceeded (see Section "6. Technical data")

### 10.3 Connecting the power supply

Connect the power supply to terminals 5(+) and 10 (-) acc. to Section "10. Electrical Connections".

A two-pole switch must be including in the supply connection where facility for switching RishDucer PT 602 is desired.

**Note:** An external supply fuse must be provided for DC supply voltage > 125 V.

## 11. Configuration

The coarse calibration is performed on the DIP switches (Fig. 8) and the fine calibration on the potentiometers marked "Zero" and "Span" (see Section "10. Electrical connection"). It is necessary to remove the cover to set the DIP switches (see Section "8. Withdrawing and Inserting the device").

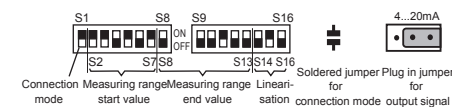


Fig.8. DIP switches, soldered jumper and jumper plug configuration the RishDucer PT 602 (illustration for the preferred single-channel version).

### 11.1. Switch positions S1 and soldered jumper (⚡) for connection mode of the resistance thermometer



As can be seen from the following table, measurement transmitters 602-1...1 and 602-1...2 can be used for **two** and **three-wire connection**. The device must be recalibrated if the connection mode is changed.

**Devices with the type designation 602-1...3 are only intended for a four-wire connection and cannot be changed.**

Connection mode	Lead resistance $R_L$	Soldered jumper	Switch position S1
Two-wire connection	$R_{L, total}$ 0...25		
	$R_{L, total}$ >25...50	closed	
Three-wire connection	25 $\Omega$ per lead		
Four-wire connection		open	

### 11.2. Switch positions (S2...S7) for measuring range start value

#### 11.2.1. Three and four-wire connection

Set DIP switches S2...S7 to the positions given in the following table for the desired minimum value of the measuring range.

#### Example 1:

Minimum value of the measuring range 820C  
Switch positions "ON-ON-OFF-OFF-OFF-ON"

Measuring range start value C	S2 ... S7	Measuring range start value C	S2 ... S7
-170 ... -149	□□□□□□	295 ... 301	□□□□□□
-149 ... -119	□□□□□□	301 ... 306	□□□□□□
-119 ... -98	□□□□□□	306 ... 315	□□□□□□
-98 ... -76	□□□□□□	315 ... 326	□□□□□□
-76 ... -58	□□□□□□	326 ... 335	□□□□□□
-58 ... -41	□□□□□□	335 ... 344	□□□□□□
-41 ... -20	□□□□□□	344 ... 350	□□□□□□
-20 ... 0	□□□□□□	350 ... 359	□□□□□□
0 ... 24	□□□□□□	359 ... 367	□□□□□□
24 ... 47	□□□□□□	367 ... 375	□□□□□□
47 ... 64	□□□□□□	375 ... 384	□□□□□□
64 ... 82	□□□□□□	384 ... 393	□□□□□□
82 ... 99	□□□□□□	393 ... 400	□□□□□□
99 ... 116	□□□□□□	400 ... 408	□□□□□□
116 ... 131	□□□□□□	408 ... 415	□□□□□□
131 ... 146	□□□□□□	415 ... 422	□□□□□□
146 ... 163	□□□□□□	422 ... 429	□□□□□□
163 ... 180	□□□□□□	429 ... 435	□□□□□□
180 ... 197	□□□□□□	435 ... 443	□□□□□□
197 ... 209	□□□□□□	443 ... 450	□□□□□□
209 ... 219	□□□□□□	450 ... 456	□□□□□□
219 ... 228	□□□□□□	456 ... 462	□□□□□□
228 ... 240	□□□□□□	462 ... 466	□□□□□□
240 ... 251	□□□□□□	466 ... 470	□□□□□□
251 ... 265	□□□□□□	470 ... 476	□□□□□□
265 ... 275	□□□□□□	476 ... 481	□□□□□□
275 ... 281	□□□□□□	481 ... 488	□□□□□□
281 ... 286	□□□□□□	488 ... 494	□□□□□□
286 ... 291	□□□□□□	494 ... 499	□□□□□□
291 ... 295	□□□□□□	499 ... 500	□□□□□□

### 11.2.2. Two-wire connection

To determine the switch positions for the desired minimum value of the measuring range, add the resistances of the sensor and the leads ( $R_{total}$ ). If the total lead resistance ( $R_{total}$ ) exceeds 25  $\Omega$ , subtract 25  $\Omega$ .

Example 2:  
 Measuring range 0...100 0C  
 Total lead resistance  $R_{total}$  35 (subtract 25  $\Omega$ )  
 The minimum value is given by sensor + lead resistance:  
 $R_{total} = 100 \Omega + 10 \Omega$

At 260C, a Pt 100 has a resistance of 110. The minimum value of the measuring range that has to be set on DIP switches S2...S7 is therefore 260C i.e. the switches positions are "ON-ON-OFF-OFF-ON-ON".

### 11.3 Switch positions for setting the span (S8...S13)

Select the desired span in the following table and place switch S8 in block 1 and switches S9...S13 in the corresponding positions.

Example 3:  
 Measuring span 616 0C  
 Switch positions "ON-ON-ON-OFF-OFF-ON"

Measuring span C	S8 ... S13	Measuring span C	S8 ... S13
50 ... 68	□□□□□□	... 445	□□□□□□
... 85	□□□□□□	... 450	□□□□□□
... 101	□□□□□□	... 458	□□□□□□
... 122	□□□□□□	... 466	□□□□□□
... 140	□□□□□□	... 477	□□□□□□
... 150	□□□□□□	... 485	□□□□□□
... 159	□□□□□□	... 490	□□□□□□
... 174	□□□□□□	... 494	□□□□□□
... 193	□□□□□□	... 502	□□□□□□
... 207	□□□□□□	... 512	□□□□□□
... 220	□□□□□□	... 519	□□□□□□
... 237	□□□□□□	... 526	□□□□□□
... 254	□□□□□□	... 535	□□□□□□
... 271	□□□□□□	... 544	□□□□□□
... 288	□□□□□□	... 553	□□□□□□
... 303	□□□□□□	... 561	□□□□□□
... 318	□□□□□□	... 570	□□□□□□
... 329	□□□□□□	... 578	□□□□□□
... 339	□□□□□□	... 584	□□□□□□
... 353	□□□□□□	... 589	□□□□□□
... 364	□□□□□□	... 597	□□□□□□
... 370	□□□□□□	... 603	□□□□□□
... 376	□□□□□□	... 606	□□□□□□
... 387	□□□□□□	... 610	□□□□□□
... 399	□□□□□□	... 616	□□□□□□
... 408	□□□□□□	... 623	□□□□□□
... 417	□□□□□□	... 628	□□□□□□
... 423	□□□□□□	... 633	□□□□□□
... 428	□□□□□□	... 640	□□□□□□
... 434	□□□□□□	... 646	□□□□□□
... 440	□□□□□□	... 700	□□□□□□

### 11.4. Switch positions (S14...S16) for linearisation

A switch combination has to be set to linearise the range that depends on the minimum value of the measuring range (TA) and the temperature range (TE - TA). Fig. 9 shows how the switch positions are determined for the example of a measuring range of 100...600C. The correct switch positions for this example are "OFF-ON-ON".

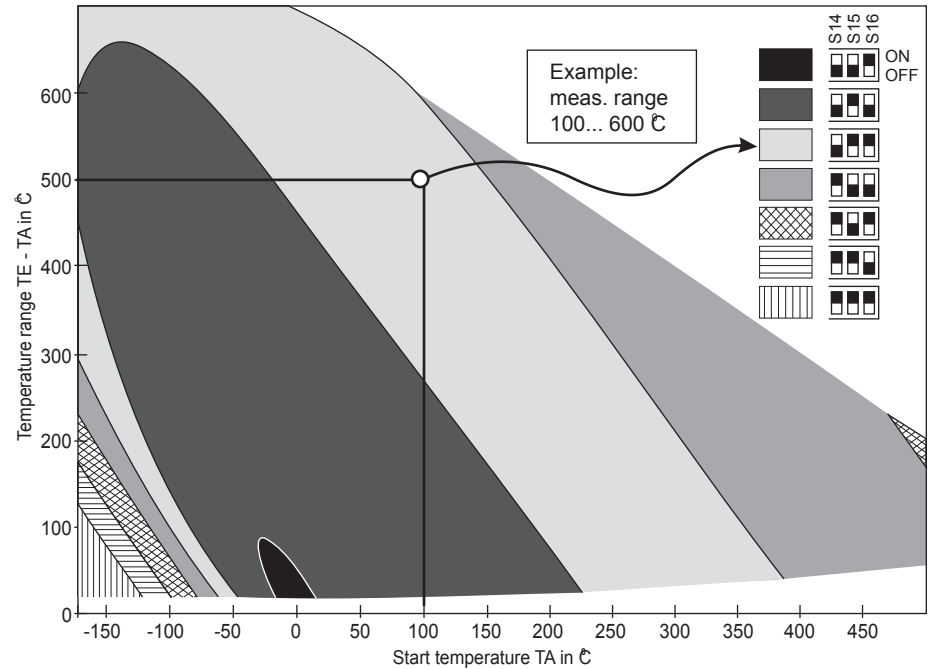


Fig. 9. Switch positions (S14...S16) for linearisation.  
 TA = Measuring range start value  
 TE = Measuring range end value

### 11.5 Jumper plug positions for output signal range

There is a jumper plug for each channel that enables the output current range to be selected (see Fig. 10).

Current [mA]	Plug-in-jumpers
0...20	□●●●
4...20	●□●●

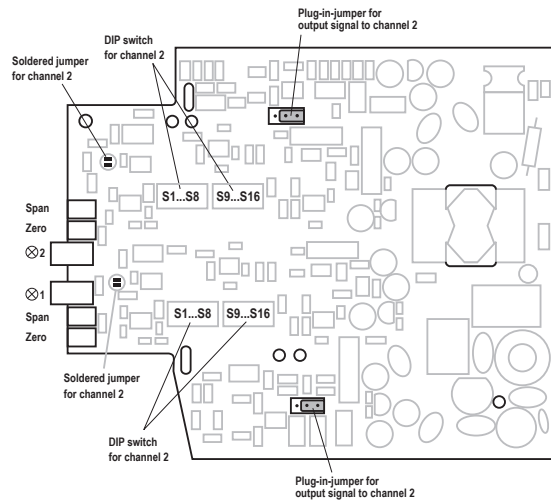


Fig. 10. Position of the DIP switches S1...S16, plug-in jumpers and soldered jumpers.

## 12. Commissioning

Switch on the measuring inputs and the power supply. The green LED's lights continuously after switching on.



The power supply unit must be capable of supplying a brief current surge when switching on. The instrument presents a low impedance at the instant of switching which requires a current I<sub>start</sub> of ...  
 ... I<sub>start</sub> 160 mA for the version with a power supply range of 24 - 60 V DC/AC  
 or  
 ... I<sub>start</sub> 160 mA for the version with a power supply range of 85 - 230 V DC/AC

## 13. Maintenance

No maintenance is required.

## 14. Releasing the transmitter

Release the transmitter from a top-hat rail as shown in Fig. 11.

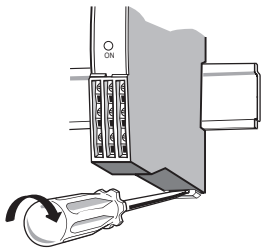


Fig. 11.

## 15. Dimensional drawings

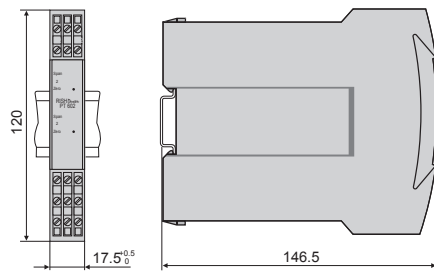


Fig. 12. in housing S17 clipped onto a top-hat rail (35 c 15 mm or 35 x 7.5 mm. acc. to EN 50 022).

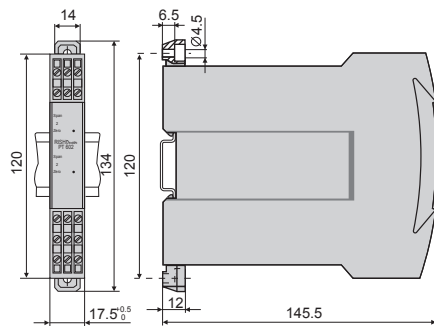


Fig. 13. in housing S17 screw hole mounting brackets pulled out.

# Notes